

Theorem Problem

SNU 4541.664A Program Analysis

Spring 2006

Note 10-1

Prof. Kwangkeun Yi

요약해석 디자인과 구현의 예

변수가 있는 정수식 프로그램의 요약해석

명령형 언어 프로그램의 요약해석

계산 실행과정의 요약해석

변수가 있는 정수식 프로그램의 요약해석

$E \rightarrow n \quad (n \in \mathbb{Z})$

| x 변수

| $E + E$

| $-E$

| let $x E_1 E_2$ 지역 변수

| if $E_1 E_2 E_3$

요약들

- 시작: 모듬의 미(*collecting semantics*)

$$\begin{array}{lcl} \mathcal{V} & \in & \textit{Exp} \rightarrow 2^{\textit{Env}} \rightarrow 2^{\mathbb{Z}} \\ \textit{Env} & = & \textit{Var} \xrightarrow{\textit{fin}} \mathbb{Z} \end{array}$$

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$$2^{\text{Env}} \rightarrow 2^{\mathbb{Z}} \xrightleftharpoons[\alpha]{\gamma} \hat{\text{Env}} \rightarrow \hat{\mathbb{Z}}, \quad 2^{\text{Env}} \xrightleftharpoons[\alpha_1]{\gamma_1} \hat{\text{Env}}, \quad 2^{\mathbb{Z}} \xrightleftharpoons[\alpha_2]{\gamma_2} \hat{\mathbb{Z}}$$

이고, 요약 의미 $\hat{\mathcal{V}} E$ 가

$$\hat{\mathcal{V}} E \sqsupseteq \alpha(\mathcal{V} E) = \alpha_2 \circ \mathcal{V} E \circ \gamma_1$$

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- 환경에서 변수간의 관계를 잊어버리기

$$\begin{array}{lll} \hat{\text{Env}} & = \text{Var} \xrightarrow{\text{fin}} 2^{\mathbb{Z}} & \alpha_1 = \lambda \Sigma. \{x \mapsto \bigcup_{\sigma \in \Sigma} (\sigma x) \mid x \in \text{Var}\} \\ \hat{\mathbb{Z}} & = 2^{\mathbb{Z}} & \alpha_2 = id \end{array}$$

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- 그리고, 변수가 가지는 정수들을 요약하기 ($\alpha_2 \neq id$)

$$\hat{\text{Env}} = \text{Var} \xrightarrow{\text{fin}} \hat{\mathbb{Z}} \quad \alpha_1 = \lambda \Sigma. \{x \mapsto \alpha_2(\bigcup_{\sigma \in \Sigma} (\sigma x)) \mid x \in \text{Var}\}$$

모듬 의미(collecting semantics)

모듬 의미함수 \mathcal{V} 는 아래와 같은 공간에서

$$\mathcal{V} \in \text{Exp} \rightarrow 2^{\text{Env}} \rightarrow 2^{\mathbb{Z}}$$

$$\Sigma \in 2^{\text{Env}}$$

$$\sigma \in \text{Env} = \text{Var} \xrightarrow{\text{fin}} \mathbb{Z}$$

조립식으로 정의된다:

$$\mathcal{V} n \Sigma = \{n\}$$

$$\mathcal{V} x \Sigma = \{\sigma x \mid \sigma \in \Sigma\}$$

$$\mathcal{V} E_1 + E_2 \Sigma = \{z_1 + z_2 \mid z_i \in \mathcal{V} E_i \Sigma\}$$

$$\mathcal{V} - E \Sigma = \{-z \mid z \in \mathcal{V} E \Sigma\}$$

$$\mathcal{V} \text{let } x E_1 E_2 \Sigma = \mathcal{V} E_2 \{\sigma \{x \mapsto v \mid \sigma \in \Sigma, v \in \mathcal{V} E_1 \Sigma\}\}$$

$$\mathcal{V} \text{if } E_1 E_2 E_3 \Sigma = \mathcal{V} E_2 (\mathcal{B} E_1 \Sigma) \cup \mathcal{V} E_3 (\neg \mathcal{B} E_1 \Sigma)$$

$$\mathcal{B} E \Sigma = \cup \{\Sigma' \mid \mathcal{V} E \Sigma' \not\ni 0, \Sigma' \subseteq \Sigma\}$$

$$\neg \mathcal{B} E \Sigma = \cup \{\Sigma' \mid \mathcal{V} E \Sigma' = \{0\}, \Sigma' \subseteq \Sigma\}$$

의미공간 요약

요약된 의미함수 $\hat{\mathcal{V}}$ 는 다음의 공간에서

$$\hat{\mathcal{V}} \in \textit{Exp} \rightarrow \hat{\textit{Env}} \rightarrow \hat{\mathbb{Z}}$$

정의되고, 의미공간 사이의 갈로아 연결

$$2^{\textit{Env}} \rightarrow 2^Z \xrightleftharpoons[\alpha]{\gamma} \hat{\textit{Env}} \rightarrow \hat{\mathbb{Z}}$$

은 각 부품의 갈로아 연결

$$2^{\textit{Env}} \xrightleftharpoons[\alpha_1]{\gamma_1} \hat{\textit{Env}} \quad \text{와} \quad 2^Z \xrightleftharpoons[\alpha_2]{\gamma_2} \hat{\mathbb{Z}}$$

를 가지고 안전하게 정의될 수 있다.

요약 의미 함수 $\hat{\mathcal{V}} E$

최선의 요약 의미함수

$$\hat{\mathcal{V}} E = \alpha(\hat{\mathcal{V}} E) = \alpha_2 \circ \mathcal{V} E \circ \gamma_1$$

의 정의:

$$\hat{\mathcal{V}} n \hat{\Sigma} = \alpha_2 \{n\}$$

$$\hat{\mathcal{V}} E_1 + E_2 \hat{\Sigma} = \alpha_2 \{v_1 + v_2 \mid v_1 \in \gamma_2(\hat{\mathcal{V}} E_1 \hat{\Sigma}), v_2 \in \gamma_2(\hat{\mathcal{V}} E_2 \hat{\Sigma})\}$$

$$\hat{\mathcal{V}} - E \hat{\Sigma} = \alpha_2 \{-v \mid v \in \gamma_2(\hat{\mathcal{V}} E \hat{\Sigma})\}$$

$$\hat{\mathcal{V}} \text{let } x E_1 E_2 \hat{\Sigma} = \hat{\mathcal{V}} E_2 (\alpha_1 \{\sigma \{x \mapsto v\} \mid \sigma \in \gamma_1(\hat{\Sigma}), v \in \gamma_2(\hat{\mathcal{V}} E_1 \hat{\Sigma})\})$$

$$\hat{\mathcal{V}} \text{if } E_1 E_2 E_3 \hat{\Sigma} = \hat{\mathcal{V}} E_2 (\alpha_2(\mathcal{B} E_1 (\gamma_1 \hat{\Sigma}))) \sqcup \hat{\mathcal{V}} E_3 (\alpha_2(\neg \mathcal{B} E_1 (\gamma_1 \hat{\Sigma})))$$

Lemma (Correctness)

$$\forall E : \alpha(\mathcal{V} E) \sqsubseteq \hat{\mathcal{V}} E$$

요약 의미함수 $\hat{\mathcal{V}} E$

또 다른 요약 의미함수의 정의:

$$\hat{\mathcal{V}} n \hat{\Sigma} = \alpha_2 \{n\}$$

$$\hat{\mathcal{V}} E_1 + E_2 \hat{\Sigma} = (\hat{\mathcal{V}} E_1 \hat{\Sigma}) \hat{+} (\hat{\mathcal{V}} E_2 \hat{\Sigma})$$

$$\hat{\mathcal{V}} - E \hat{\Sigma} = \hat{-}(\hat{\mathcal{V}} E \hat{\Sigma})$$

$$\hat{\mathcal{V}} \text{let } x E_1 E_2 \hat{\Sigma} = \hat{\mathcal{V}} E_2 (\hat{\Sigma}\{x \mapsto \hat{\mathcal{V}} E_1 \hat{\Sigma}\})$$

$$\hat{\mathcal{V}} \text{if } E_1 E_2 E_3 \hat{\Sigma} = (\hat{\mathcal{V}} E_2 (\hat{\mathcal{B}} E_1 \hat{\Sigma})) \sqcup (\hat{\mathcal{V}} E_3 (\neg \hat{\mathcal{B}} E_1 \hat{\Sigma}))$$

여기서 $\hat{+}$, $\hat{-}$, $\cdot\{x \mapsto \cdot\}$, $\hat{\mathcal{B}}$, $\neg \hat{\mathcal{B}}$ 는 해당 연산들을 안전하게 요약한 것들이어야.

Lemma (Correctness)

$$\forall E : \alpha(\mathcal{V} E) \sqsubseteq \hat{\mathcal{V}} E$$

명령형 언어 프로그램의 요약해석

$$\begin{array}{lcl} C & \rightarrow & \text{skip} \mid x := E \mid C ; C \\ & | & \text{if } B \ C \ C \\ & | & \text{while } B \ C \\ E & \rightarrow & n \quad (n \in \mathbb{Z}) \mid x \\ & | & E + E \mid B \quad (\text{boolean expr}) \end{array}$$

의 미공간은

$$\begin{array}{lcl} \mathcal{C} \ C & \in & 2^{\text{Memory}} \rightarrow 2^{\text{Memory}} \\ \mathcal{V} \ E & \in & 2^{\text{Memory}} \rightarrow 2^{\text{Value}} \\ \mathcal{B} \ B & \in & 2^{\text{Memory}} \rightarrow 2^{\text{Memory}} \\ \text{Memory} & = & \text{Loc} \xrightarrow{\text{fin}} \text{Value} \\ \text{Value} & = & \mathbb{Z} + \mathbb{B} \\ \text{Loc} & = & \text{Var} \\ \mathbb{B} & = & \{T, F\} \end{array}$$

$$m \in Memory \quad M \in 2^{Memory}$$

$$\mathcal{C} \text{ skip } M = M$$

$$\mathcal{C} x := E M = \{m\{x \mapsto v\} \mid m \in M, v \in \mathcal{V} E M\}$$

$$\mathcal{C} C_1 ; C_2 M = \mathcal{C} C_2 (\mathcal{C} C_1 M)$$

$$\mathcal{C} \text{ if } B C_1 C_2 M = \mathcal{C} C_1 (\mathcal{B} B M) \cup \mathcal{C} C_2 (\mathcal{B} \neg B M)$$

$$\mathcal{C} \text{ while } B C M = \mathcal{B} \neg B (fix \lambda X. M \cup \mathcal{C} C (\mathcal{B} B X))$$

$$\mathcal{V} n M = \{n\}$$

$$\mathcal{V} x M = \{m x \mid m \in M\}$$

$$\mathcal{V} E_1 + E_2 M = \{v_1 + v_2 \mid v_1 \in \mathcal{V} E_1 M, v_2 \in \mathcal{V} E_2 M\}$$

$$\mathcal{B} B M = \cup\{M' \mid \mathcal{V} B M' = \{T\}, M' \subseteq M\}$$

요약

$$\hat{\mathcal{C}} C \in \hat{Memory} \rightarrow \hat{Memory}$$

$$\hat{\mathcal{V}} E \in \hat{Memory} \rightarrow \hat{Value}$$

$$\hat{\mathcal{B}} B \in \hat{Memory} \rightarrow \hat{Memory}$$

갈로아 연결 된 요약공간

$$2^{Memory} \xrightleftharpoons[\alpha_1]{\gamma_1} \hat{Memory} \qquad 2^{Value} \xrightleftharpoons[\alpha_2]{\gamma_2} \hat{Value}$$

$$\begin{aligned}
 \hat{\mathcal{C}} \text{ skip } \hat{m} &= \hat{m} \\
 \hat{\mathcal{C}} x := E \hat{m} &= \alpha_1 \{ m \{ x \mapsto v \} \mid m \in \gamma_1 \hat{m}, v \in \gamma_2 (\hat{\mathcal{V}} E \hat{m}) \} \\
 \hat{\mathcal{C}} C_1 ; C_2 \hat{m} &= \hat{\mathcal{C}} C_2 (\hat{\mathcal{C}} C_1 \hat{m}) \\
 \hat{\mathcal{C}} \text{ if } B C_1 C_2 \hat{m} &= \hat{\mathcal{C}} C_1 (\hat{\mathcal{B}} B \hat{m}) \sqcup \hat{\mathcal{C}} C_2 (\hat{\mathcal{B}} \neg B \hat{m}) \\
 \hat{\mathcal{C}} \text{ while } B C \hat{m} &= \hat{\mathcal{B}} \neg B (fix \lambda \hat{x}. \hat{m} \sqcup \hat{\mathcal{C}} C (\hat{\mathcal{B}} B \hat{x})) \\
 \hat{\mathcal{V}} n \hat{m} &= \alpha_2 \{ n \} \\
 \hat{\mathcal{V}} x \hat{m} &= \hat{m} x \\
 \hat{\mathcal{V}} E_1 + E_2 \hat{m} &= \alpha_2 \{ v_1 + v_2 \mid v_1 \in \gamma_2 (\hat{\mathcal{V}} E_1 \hat{m}), v_2 \in \gamma_2 (\hat{\mathcal{V}} E_2 \hat{m}) \} \\
 \hat{\mathcal{B}} B \hat{m} &= \alpha_1 (\cup \{ M' \mid \mathcal{V} B M' = \{ T \}, \hat{M}' \subseteq \gamma_1 \hat{m} \})
 \end{aligned}$$

Lemma (Correctness)

$$\forall C : \alpha(\mathcal{C} C) \sqsubseteq \hat{\mathcal{C}} C$$



구현

주어진 프로그램 C 와, 관심있는 초기 메모리 \hat{m}_0 에 대해서 조립식으로 정의된

$$\hat{\mathcal{C}} C \hat{m}_0$$

를 계산.

- 이때 C 안에 있는 `while E C'`에 대해서 $fix \hat{F} \in \hat{Memory}$ 의 계산은

$$\bigsqcup_{i \in \mathbb{N}} \hat{F}^i(\perp_{\hat{Memory}})$$

으로.

- 위의 계산이 끝나지 않거나 시간이 너무 오래 걸릴 수 있으면 축지법(\triangledown)과 좁히기(\triangle)를 이용

$$\begin{aligned}
 \hat{\mathcal{C}} \text{ skip } \hat{m} &= \hat{m} \\
 \hat{\mathcal{C}} x := E \hat{m} &= \alpha_1\{m\{x \mapsto v\} \mid m \in \gamma_1 \hat{m}, v \in \gamma_2(\hat{\mathcal{V}} E \hat{m})\} \\
 \hat{\mathcal{C}} C_1 ; C_2 \hat{m} &= \hat{\mathcal{C}} C_2 (\hat{\mathcal{C}} C_1 \hat{m}) \\
 \hat{\mathcal{C}} \text{ if } B C_1 C_2 \hat{m} &= \hat{\mathcal{C}} C_1 (\hat{\mathcal{B}} B \hat{m}) \sqcup \hat{\mathcal{C}} C_2 (\hat{\mathcal{B}} \neg B \hat{m}) \\
 \hat{\mathcal{C}} \text{ while } B C \hat{m} &= \hat{\mathcal{B}} \neg B (\text{Narrow}(\text{Widen}(\lambda \hat{x}. \hat{m} \sqcup \hat{\mathcal{C}} C (\hat{\mathcal{B}} B \hat{x})))) \\
 \hat{\mathcal{V}} n \hat{m} &= \alpha_2\{n\} \\
 \hat{\mathcal{V}} x \hat{m} &= \hat{m} x \\
 \hat{\mathcal{V}} E_1 + E_2 \hat{m} &= \alpha_2\{v_1 + v_2 \mid v_1 \in \gamma_2(\hat{\mathcal{V}} E_1 \hat{m}), v_2 \in \gamma_2(\hat{\mathcal{V}} E_2 \hat{m})\} \\
 \hat{\mathcal{B}} B \hat{m} &= \alpha_1(\cup\{M' \mid \mathcal{V} B M' = \{T\}, M' \subseteq \gamma_1 \hat{m}\})
 \end{aligned}$$

$$Widen(\hat{F}) = \lim_{i \in \mathbb{N}} \begin{cases} \hat{Y}_0 &= \perp_{Memory} \\ \hat{Y}_{i+1} &= \begin{cases} \hat{Y}_i &\text{if } \hat{F}(\hat{Y}_i) \sqsubseteq \hat{Y}_i \\ \hat{Y}_i \bigtriangledown \hat{F}(\hat{Y}_i) &\text{o.w.} \end{cases} \end{cases}$$

$$Narrow(\hat{m}) = \lim_{i \in \mathbb{N}} \begin{cases} \hat{Z}_0 &= \hat{m} \\ \hat{Z}_{i+1} &= \hat{Z}_i \triangle \hat{F}(\hat{Z}_i) \end{cases}$$

계산 실행과정을 요약하는 방안들

프로그램 C 의 의미 $\llbracket C \rrbracket$ 는 C 가 실행되면서 가질 수 있는 기계상태들의 (유한 혹은 무한한) 모든 족적들

$$\llbracket C \rrbracket \in 2^{\text{Trace}}$$

$$\tau, \tau_0\tau_1 \cdots \tau_n \in \text{Trace} = \text{State}^\omega$$

$$\text{State} = \text{Command} \times \text{Memory} \times \cdots$$

$$2^{Trace} \xrightleftharpoons[\alpha]{\gamma} \hat{Trace}$$

$\xrightarrow{\alpha_0}$ Trace of set of states: sequence of set of states appearing at a given time along at least one of the traces

$$\alpha_0(X) = \lambda i. \{\tau_i \mid \tau \in X, 0 \leq i < |\tau|\}$$

$\xrightarrow{\alpha_1}$ Set of reachable states (global invariant): set of states appearing at least once along a trace

$$\alpha_1(Y) = \bigcup \{Y(i) \mid 0 \leq i < |Y|\}$$

$\xrightarrow{\alpha_2}$ Partitioned set of reachable states (local invariant): project along each control point $\in \Delta$

$$\alpha_2(\{\langle c_i, s_i \rangle \mid i \in \Delta\}) = \lambda c. \{s_i \mid i \in \Delta, c = c_i\}$$